



# NetAI™

## Understanding GNN vs LLM based AIOPs for Autonomous Network Operations

CHINOG 13 CHICAGO, IL

27-28 May 2026

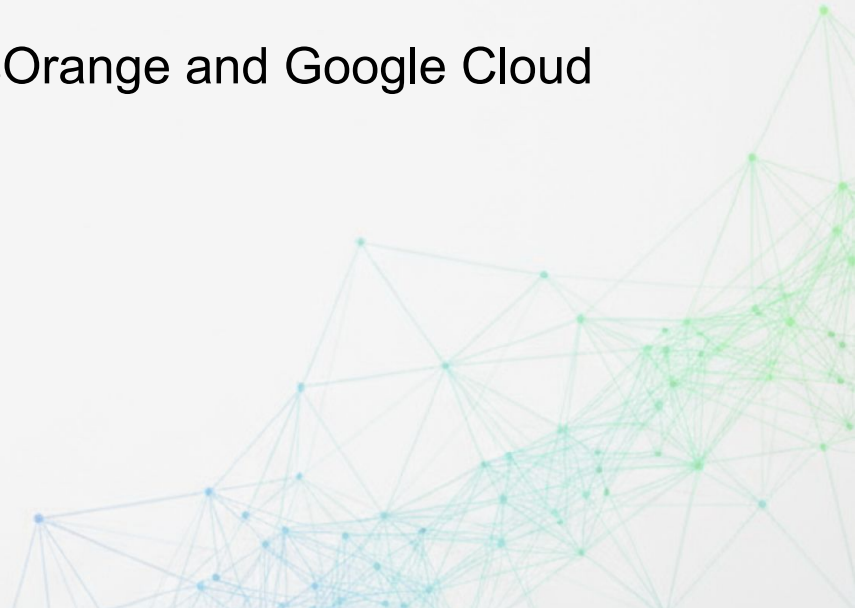
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# Agenda

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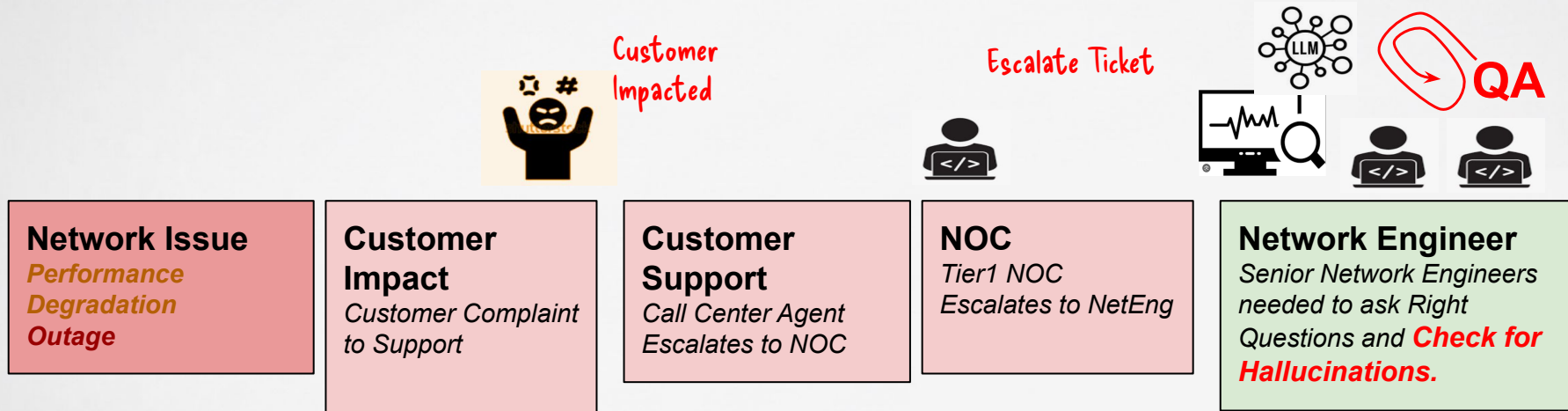
- Why current AIOps still leaves teams doing manual RCA
- What is Missing in the existing stack
- AIOps Architectural Patterns
- GNN Introduction
- Operational Use Case Study - POC MasOrange and Google Cloud
- Limitations and Scope
- Questions



# Problem: Today's Workflow is Reactive, Manual and Expensive

GAP - Non Deterministic Root Cause

Wait for Failure -> 4 Manual Touch Points -> Upset Customer !

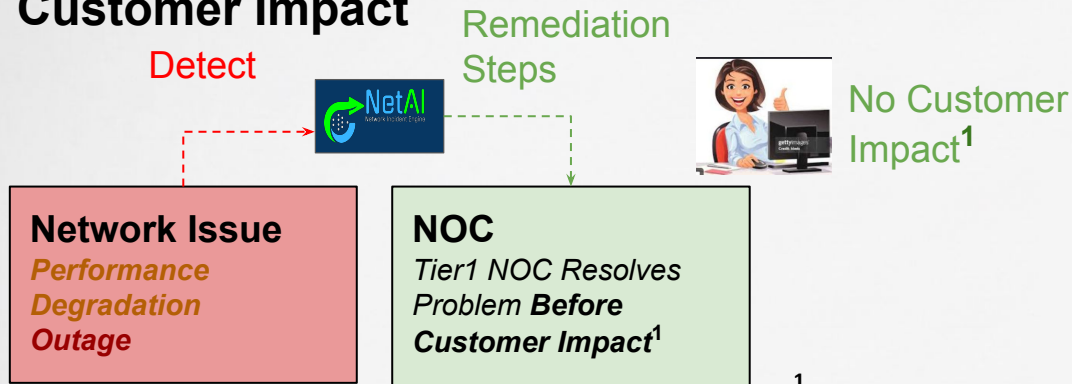


Hours to Days

GAP - Most Current AIOps Platforms Still Leave Root-Cause Validation to Operators.

# Solution: Automated Workflow: Proactive, No Customer Impact

Proactively Detect and Guide Remediation with Fewer Touch Points and Lower Customer Impact



Seconds to Minutes



How ?

Graph Neural Networks (GNNs)

Provide Deterministic Answers:

- Root Cause
- Associated Correlated Events

Why ?

Better Customer Experience

- ➔ Proactive
- Network Operations Efficiency
- ➔ Faster Resolution

<sup>1</sup> Some Faults cannot be predicted, Ex. Fiber Cut, In this case Customer Impact is Minimized, Not Avoided

# The Missing Layer Between Observability and Automation

Network Telemetry

Adapter Layer

**Deterministic Root Cause + Remediation Steps**

- Ingest telemetry from Current Tools
- Determine Root Cause
- Verify Root Cause
- Determine Remediation
- Trigger existing in-house automation or operator workflows

Agent Remediates Root Cause

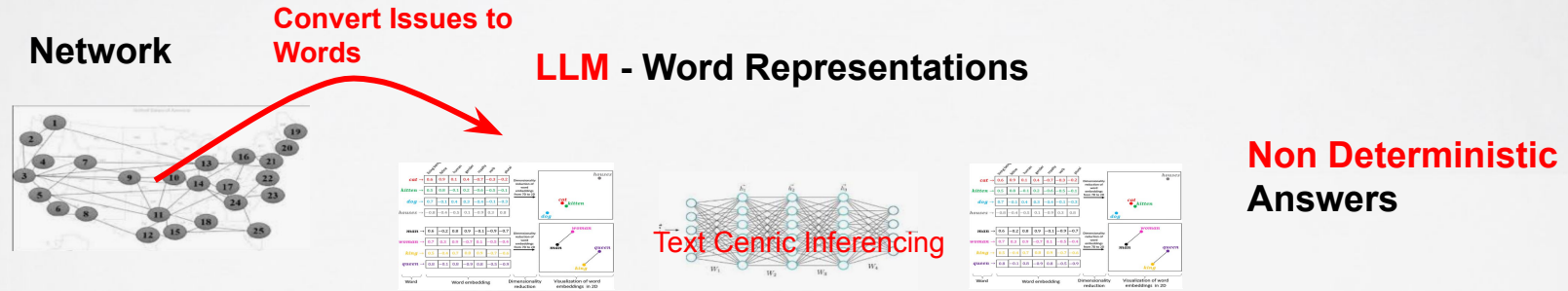


NOC Engineer Remediates Root Cause

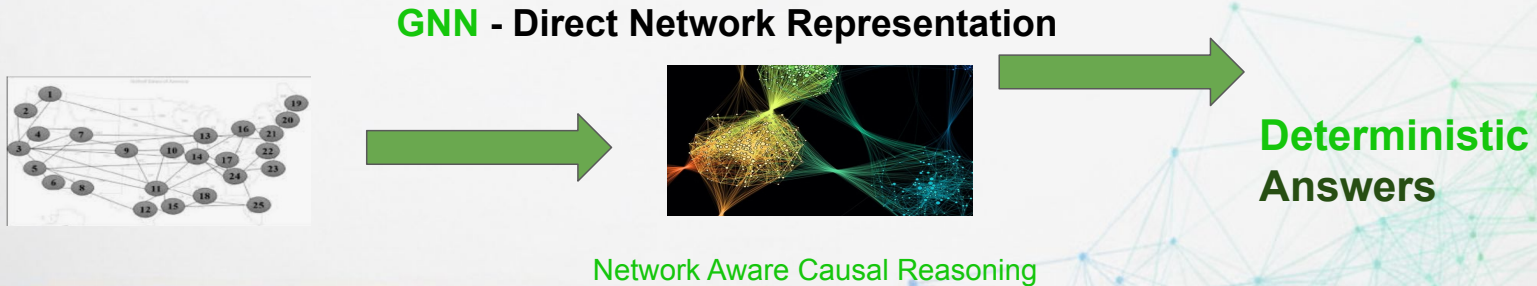
In House Automation

# AIOPS Achitectures - Whats the Main Difference?

LLM based workflows require Human QA on hundreds of Alarms



GNN based workflows process Burst of Alarms → Reduce to Root Alarms



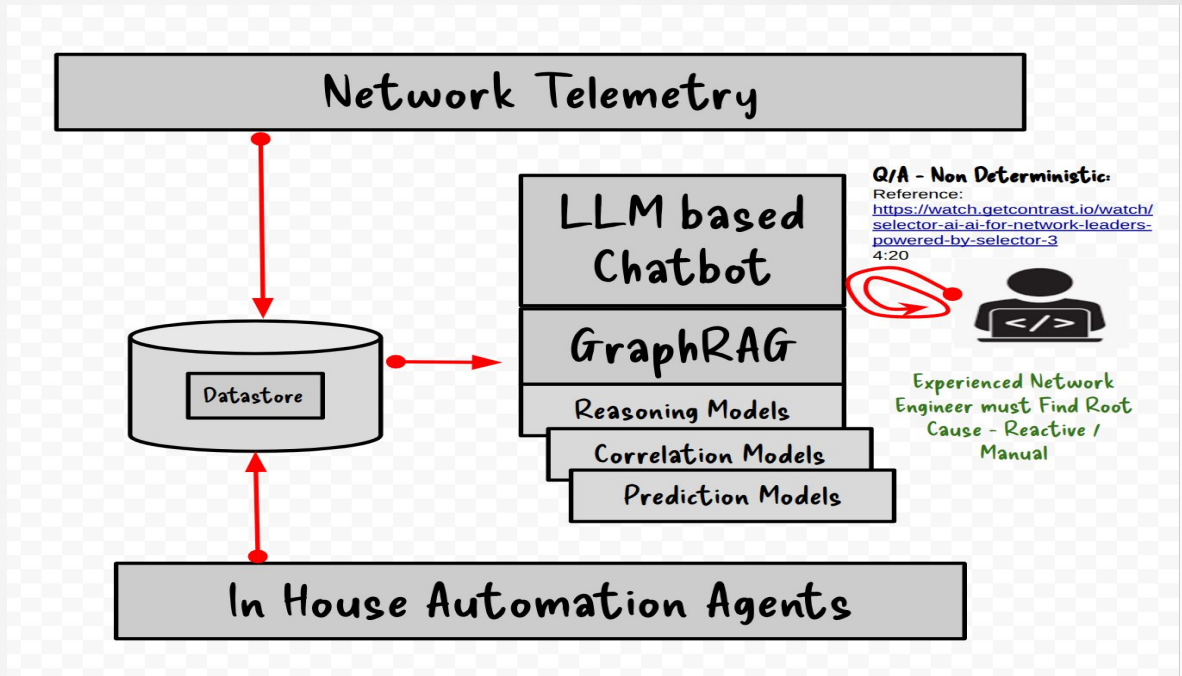
# AIOPS Systems Architecture - **Non Deterministic**

Non Deterministic Approach requires Experienced Network Engineer to ask Correct Questions

1. **Reactive**
2. **Starts with All Alarms**
3. **Manual**
4. **Requires Experienced Network Engineer to ask Right Questions due to Non Deterministic Answers - “..Its up to the Engineer to go on the right Path..”**

See Reference: 4:20

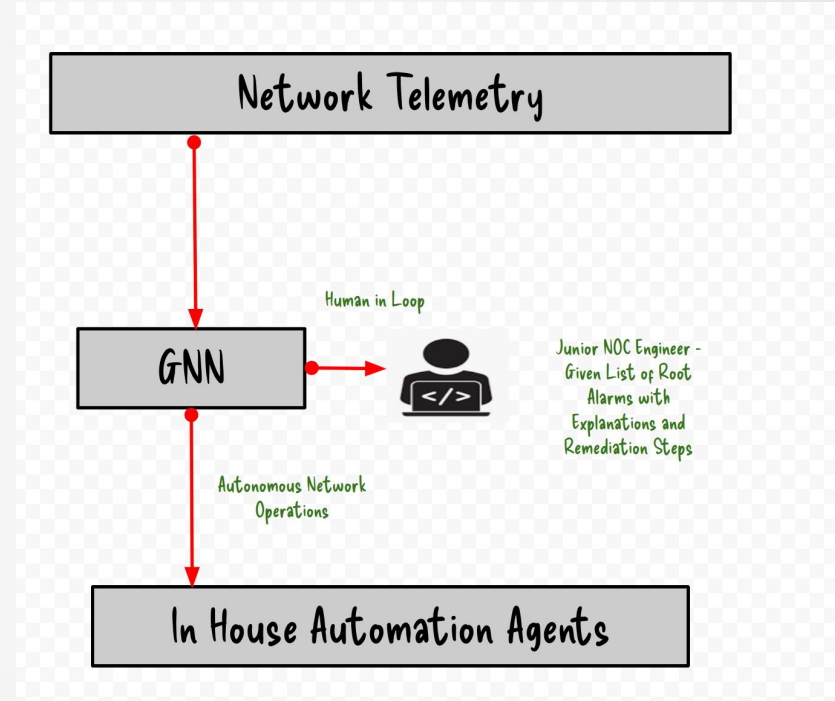
<https://watch.getcontrast.io/watch-selector-ai-for-network-leaders-powered-by-selector-3>



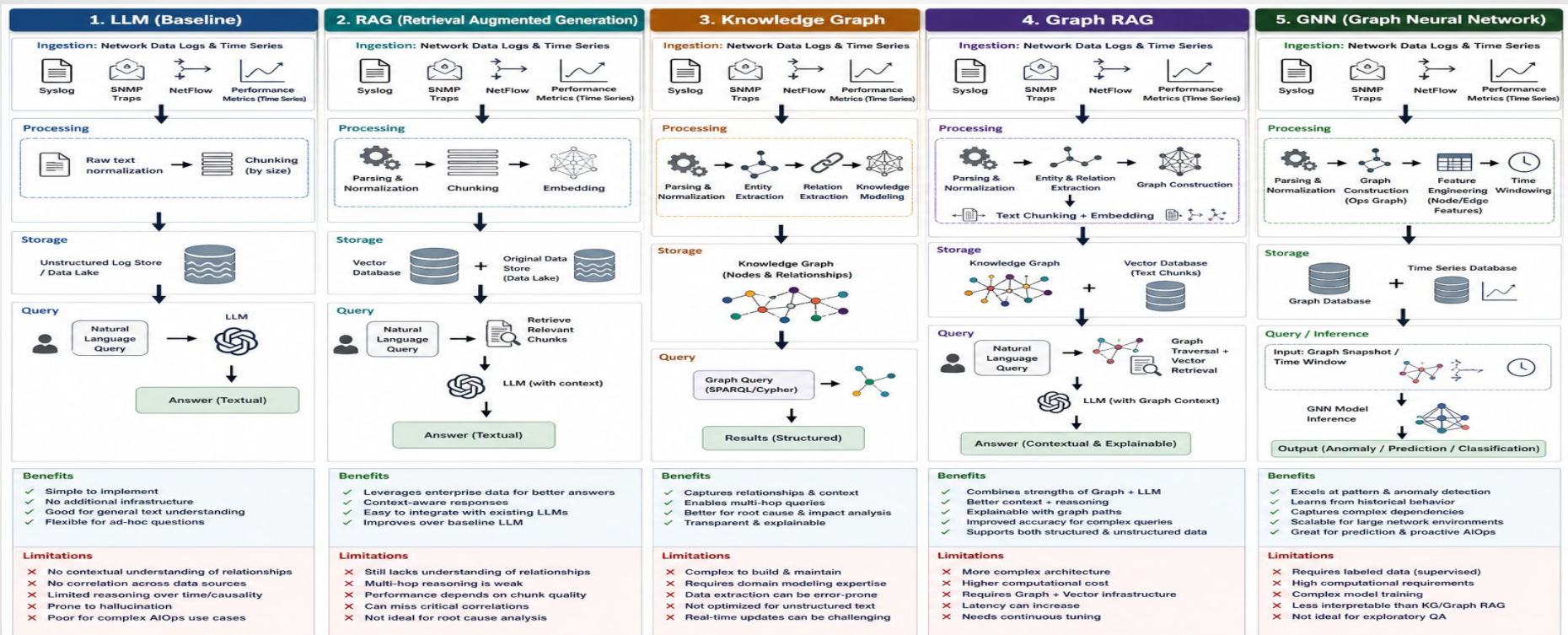
# AIOPS System Architecture – **Deterministic**

Deterministic Approach enables Automation

1. Ingest from Existing Observability Platforms or Direct
2. **Root Cause -> Remediation**
3. Trigger Existing In House Automation Agents
4. No Rip-and-Replace



# AIOps Architectural Patterns - Reference



💡 All approaches benefit from high-quality data, proper governance, and continuous feedback.

# GNN Introduction

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What is a Graph Neural Network?

- *Class of Neural Networks that operate on Graph Data*

Why does it matter in Network AIOPS?

- *Networks map directly to Input Graph Data that can be understood by GNN*



# GNN Introduction

Idea: Map Network to Node and Link Embeddings(Vectors)

Direct Representation of:

- Network Elements
- Relationships

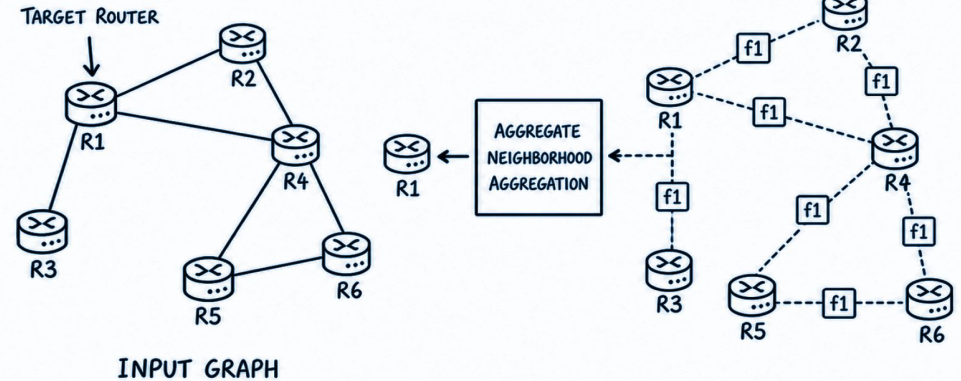
Maps to

Graph Data

- can be processed by AI

## Idea: Aggregate Neighbors

- Key idea: Generate node embeddings based on local network neighborhoods



# GNN Introduction to basic graph computations

## Main Idea:

- Data Maps to Model - Direct Representation of Real World Network
- Model Captures:
  - Relationships between Routers and Links
  - Fault Propagation Patterns
- Learns -> Becomes Smarter Over Time for that Particular Customer

## GNN message passing equations

### Generic message passing:

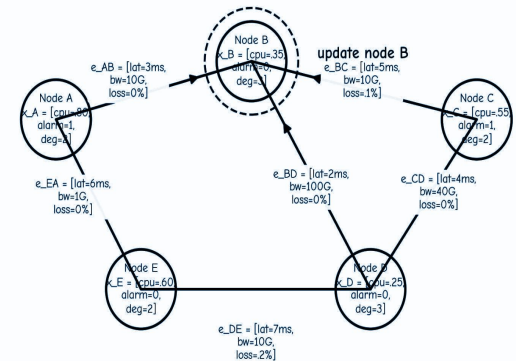
$$m_v(k+1) = \text{AGG}(\{ \text{phi}(h_u(k), e_{uv}) : u \in N(v) \})$$
$$h_v(k+1) = \text{UPDATE}(h_v(k), m_v(k+1))$$

### For the diagram, if we update node B:

$$m_B(k+1) = \text{AGG}(\{ \text{phi}(h_A(k), e_{AB}), \text{phi}(h_C(k), e_{BC}), \text{phi}(h_D(k), e_{BD}) \})$$
$$h_B(k+1) = \text{UPDATE}(h_B(k), m_B(k+1))$$

Here  $h_A, h_C, h_D$  come from the node features,  
and  $e_{AB}, e_{BC}, e_{BD}$  come from the labeled link features.

5-node graph for GNN message passing



Each node has features  $x_v$ . Each link has features  $e_{uv}$ . Messages flow from neighbors into node B.

# GNN Introduction - basic computations simplified

Target Router =  $v$ , Neighbor Routers =  $u$ ,  $x$  = Router Features,  $h$  = latent state,  $B_v, W$  = learned Weights

What is  $f$ ?

Initial 0-th layer embeddings are equal to node features

$$h_v^0 = x_v$$

embedding of  $v$  at layer  $k$

$$h_v^{(k+1)} = \sigma\left(W_k \sum_{u \in N(v)} \frac{h_u^{(k)}}{|N(v)|} + B_k h_v^{(k)}\right), \forall k \in \{0, \dots, K-1\}$$

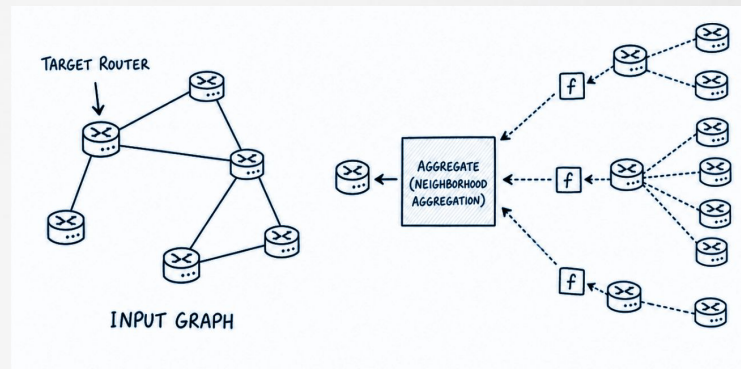
Average of neighbor's previous layer embeddings

Total number of layers

Embedding after  $K$  layers of neighborhood aggregation

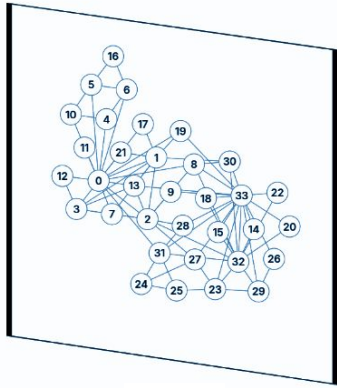
Non-linearity (e.g., ReLU)

Notice summation is a permutation invariant function.

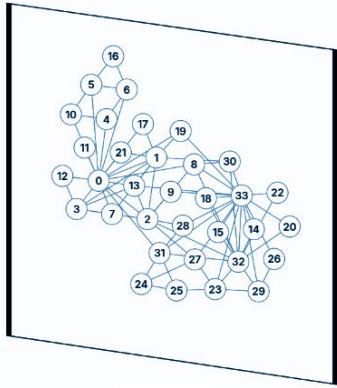


# GNN Introduction - Visual explanation

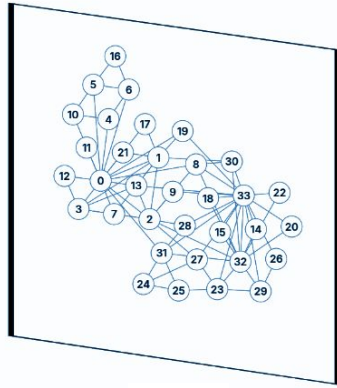
Sequence of Iterations on computing a Node Latent State - 4



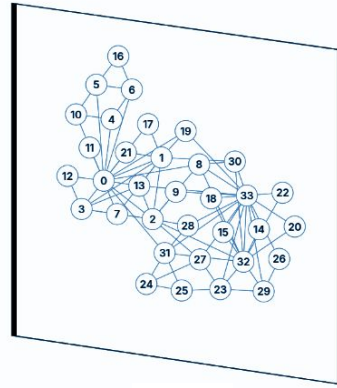
h<sub>0</sub>



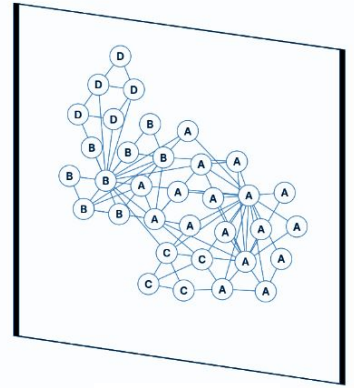
h<sub>1</sub>



h<sub>2</sub>



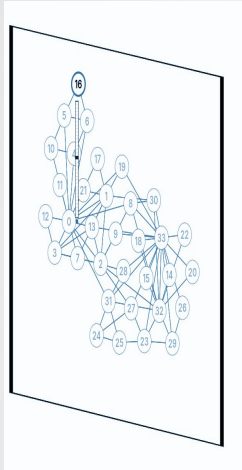
h<sub>3</sub>



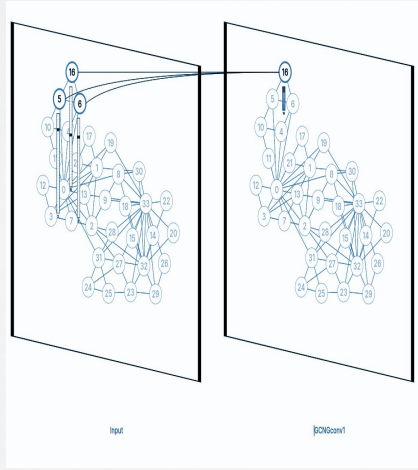
Result

# GNN Introduction - Computation of Target Node

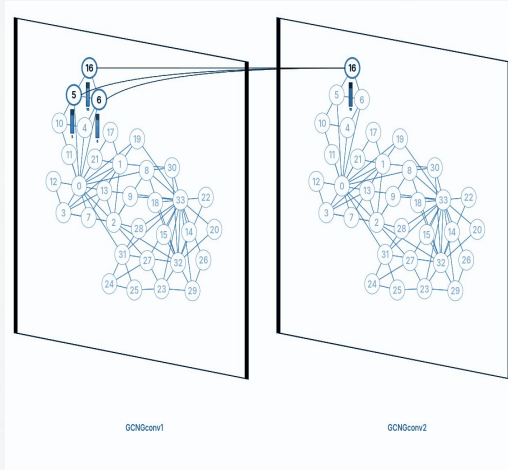
## Steps



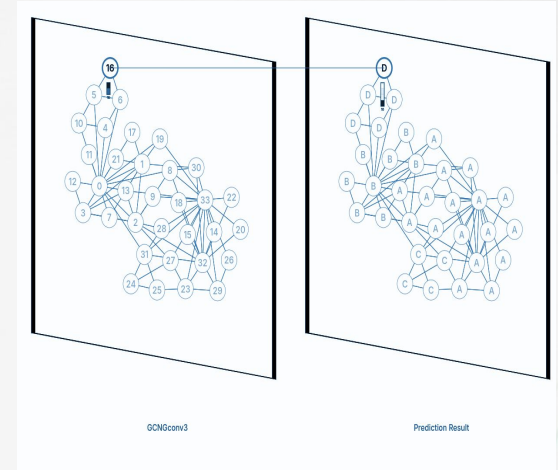
Compute  $h_0$   
- Router  
Feature Vector



Compute  $h_1$



Compute  $h_2$



Compute  $h_3$ , then  
mapping  $h_3$  to class range  
= Result

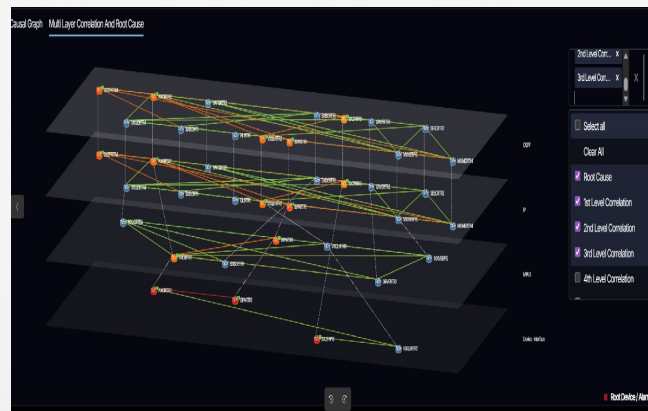
# Case Study - large European Mobile Operator

## Mobile Operator was able to prove Autonomous Network Operation using GNN - MWC 2026, Blogs

- ❑ **Incident:** Engineer made Configuration Change Error
- ❑ **Output:** Root Cause + Correlated Alarms, Explanations, Remediation
- ❑ **Operator Action:** Verified Explanations, Followed Remediation Steps
- ❑ **Business Result:** Reduced diagnosis from hours of manual triage to a validated root-cause workflow in minutes.



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Incident Summary
On February 25, 2026 an OSPF-origination issue was detected on POWTRT2 ("OSPF OriginateLSA"). Within seconds several other routers reported "ospfVl1StateChange" events while still showing full adjacencies. No alarmstream routing or resiliability problems were recorded - there are no impact alarms.
1) Root Cause Event
Device: POWTRT2
Alarm: ospfVl1StateChangeLSA
Detail excerpt: "Issues with LSA origination...the router has not originated router LSAs with maximum metric."
This alarm marks the first observable problem - the OSPF process failed to originate LSAs correctly.
2) Direct Correlated Alarms
Device Alarm Detail quote
OXDRTR1: ospfVl1IFStateChange - stable adjacency ... no counters indicating failures ...
POWTRT2: ospfVl1IFStateChange - neighbor 10.80.10.4 ... in FULL/BDR state ... no ospf errors ...
BXZFRTR4: ospfVl1IFStateChange - neighbor 10.80.10.4 ... in FULL/BDR state ... no ospf errors ...
All three correlate back to the same root UUID (a86c7145...). They all report virtual interface state changes occurring immediately after the LSA origination failure.
3) Secondary Impact Alarms
None - the incident payload contains zero impact entries.
4) Time Ordered Sequence & Causal Chain
09:05:25 POWTRT2 - ospfVl1StateChange - root
|
|--- OXDRTR1: ospfVl1IFStateChange - correlates
|
|--- POWTRT2: ospfVl1IFStateChange - correlates
|
|--- BXZFRTR4: ospfVl1IFStateChange - correlates
At 09:05:25 POWTRT2's OSPF process could not generate LSAs.
Four seconds later OXDRTR1 logged a virtual-if state change even though its neighbor remained FULL/BDR.
One second later POWTRT2 itself logged another virtual-if state change.
A minute later BXZFRTR4 also logged such a change.
Each subsequent alarm references the original LSA failure through the link relations supplied.
5) Time Diagram
Root: ospfVl1StateChange (POWTRT2)
|
|--- OXDRTR1: ospfVl1IFStateChange
|
|--- POWTRT2: ospfVl1IFStateChange
|
|--- BXZFRTR4: ospfVl1IFStateChange
Shared impact nodes do not exist because no impact alarms appear.
6) Remediation Steps
Immediate Triage
Verify system clocks on POWTRT2, OXDRTR1, BXZFRTR4 - small timestamp gaps can mislead correlation.
Confirm OSPF process health on POWTRT2 (show processes ospf, debug ospf packet) to see why LSAs weren't generated.
Check memory/usage upon POWTRT2, resource exhaustion often stops LSA origination.
Likely Fix Actions
Restart the OSPF process on POWTRT2 (show ip ospf process, shutdown)
If restart fails, reload the entire device or upgrade firmware when known bugs affect LSA generation.
Ensure correct OSPF area configurations (area IDs, authentication) so LSAs aren't silently dropped.
Validation Checks
After restarting, run show ip ospf database neighbor on POWTRT2 to verify new LSAs appear.
On neighboring routers (OXDRTR1, BXZFRTR4), check show ip ospf neighbor - they should now display proper metrics and no state-change alarms.
Monitor for any recurrence of ospfVl1IFStateChange; absence confirms resolution.
No anomalies were flagged in the payload, so data quality is considered acceptable.
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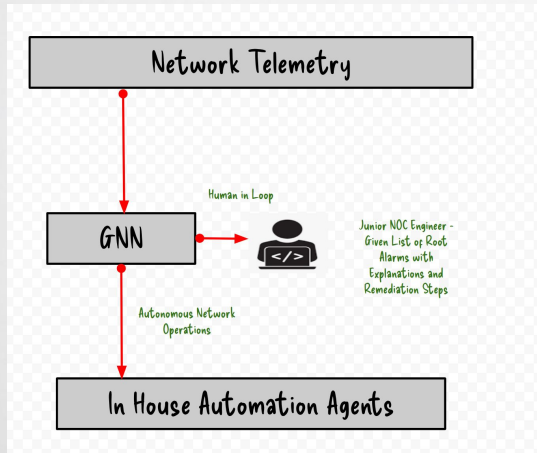
### Reference:

<https://cloud.google.com/blog/topics/telecommunications/autonomous-networks-at-mwc-2026>

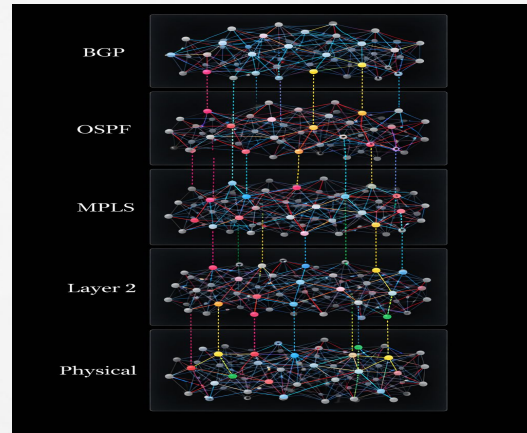
# How It Works

1. Ingest Telemetry, Alarms, Topology, Logs, Configurations from Existing Repositories or Directly
2. Build Topology aware Causal Reasoning across Network
3. Output Root Cause, Associated Correlated Alarms, Blast Radius and Remediation Guidance
4. Feed Remediation to NOC Engineer or Automation

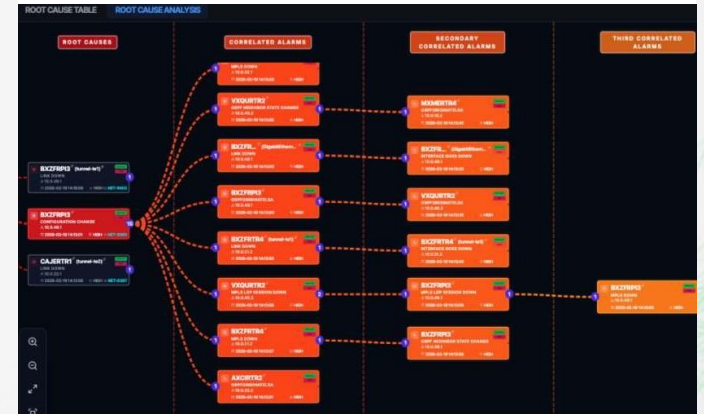
Pipeline - Autonomous Ready



GNN



Root Cause and Associated Correlated Alarms



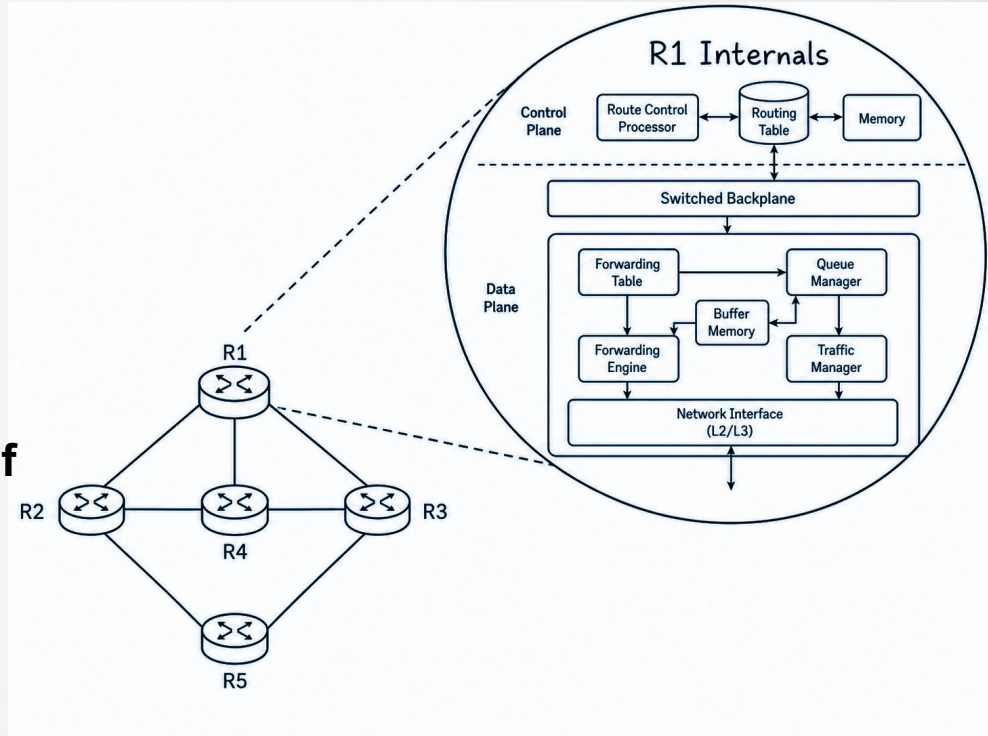
# Limitations and Scope - Level of Abstraction that Matters

## Suitable Class of Problems - NetOps

- ❑ Burst of Alarms - Finds Independent Root Causes and Associated Correlated Alarms
- ❑ Multi Layer, understands NS EW operational network relationships
- ❑ Intermittent Problems, Anomalies that are materially significant and known to cause outages

## Unsuitable Class of Problems - What If

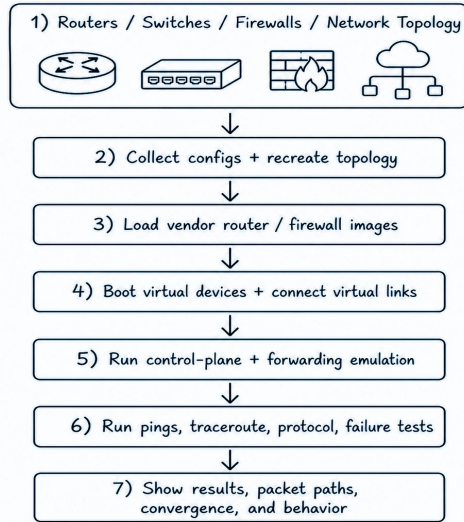
- ❑ Q/A Path Analysis - Forward Networks
- ❑ Text Q/A - Ideal for LLM
- ❑ Packet



# Limitations and Scope - Digital Twin - Usually GNS3

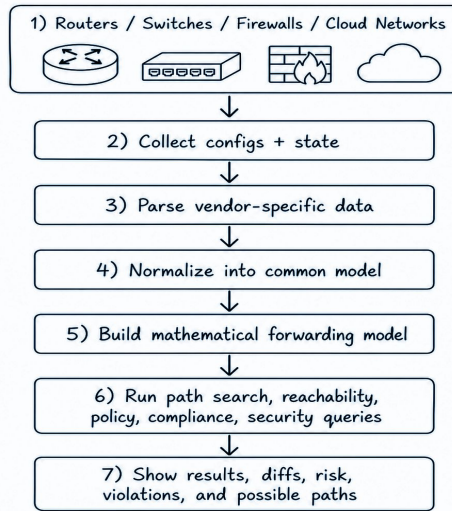
Router Emulator: GNS3  
Device Behaviour

Conceptual Diagram of a Router-Image Emulator



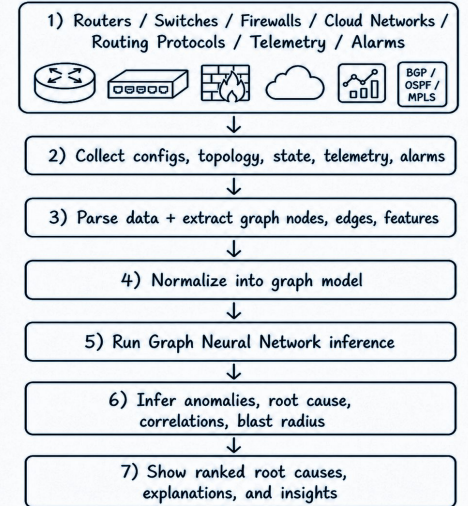
Forwarding Plane Mathematical Model  
Packet Reachability Behaviour

Conceptual Diagram of a Forward Networks Digital Twin



A GNN emulates the Failure-Propagation behavior of the network

Conceptual Diagram of a GNN-Based Network Model



# Limitations and Scope

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## Suitable Class of Problems - Optimized for Network Operations

- Deterministic Root Cause and Causal Hierarchy
- Ensemble of Node, Edge, SubGraph, Multi Layers
- Why?
  - ❑ **GNNs** learn from Structure and Fault Propagation Patterns
  - ❑ GNN improves with customer-specific network history over time

## Unsuitable Class of Problems

- Text Simple QA - Ideal for LLM
- Path Analysis - Ideal for Forwarding Plane emulators based on Mathematical Device Models
- Device internal behaviour - Device emulators



# NetAI

Thank you

